

Graphical Symplectic Algebra

ZX seminar, 7 February 2024



Relations

Relations

- a **relation** $X \rightarrow Y$ is a subset of $2^{X \times Y}$;
- we can compose a pair of relations $R : X \rightarrow Y$ and $T : Y \rightarrow Z$:
- there are identities: *relations form a category*
- **important example**: functions can be thought of as relations
- monoidal product: cartesian product

Linear & affine relations

Let $\mathbb{K}$ be a field, and X, Y, Z $\mathbb{K}$ -linear spaces.

- a **linear/affine** relation $X \rightarrow Y$ is a linear/affine *subspace* of $X \oplus Y$;
- we can compose a pair of linear/affine relations $R : X \rightarrow Y$ and $T : Y \rightarrow Z$;
- there are identities: *linear/affine relations form a category*
- **important example**: linear/affine maps can be thought of as linear/affine relations
- monoidal product: direct sum
- compact structure

- **symplectic form**: $\omega : X \oplus X \rightarrow \mathbb{R}$ that is:
 - bilinear;
 - alternating: $\omega(x, x) = 0$;
 - non-degenerate: $\omega(x, y) = 0$ for all x implies $y = 0$;
- **symplectomorphisms** $S : X \rightarrow Y$ s.t. $\omega_Y(Sx, Sy) = \omega_X(x, y)$
- subspaces:
 - *isotropic* if $S \subseteq S^\omega$ (so that for all $\vec{s}, \vec{t} \in S$, $\omega(\vec{t}, \vec{s}) = 0$);
 - *coisotropic* if $S^\omega \subseteq S$;
 - **Lagrangian** if it is both isotropic and coisotropic (so that $S = S^\omega$).

Affine Lagrangian relations

- an **affine Lagrangian** relation $X \rightarrow Y$ is a affine Lagrangian *subspace* of $X \oplus Y$;
- we can compose a pair of affine Lagrangian relations $R : X \rightarrow Y$ and $T : Y \rightarrow Z$:
- there are identities: *affine Lagrangian relations form a category*
- **important example**: affine symplectomorphisms can be thought of as affine Lagrangian relations
- monoidal product: direct sum
- compact structure: also inherited from linear relations

By varying the field F , we can obtain semantics for a fairly wide range of subject areas:

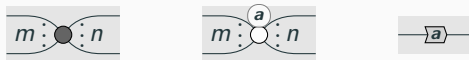
- classical mechanics;
- electrical circuits;
- (stabiliser) quantum mechanics;

Diagrammatics

Spiders: only connectivity matters!

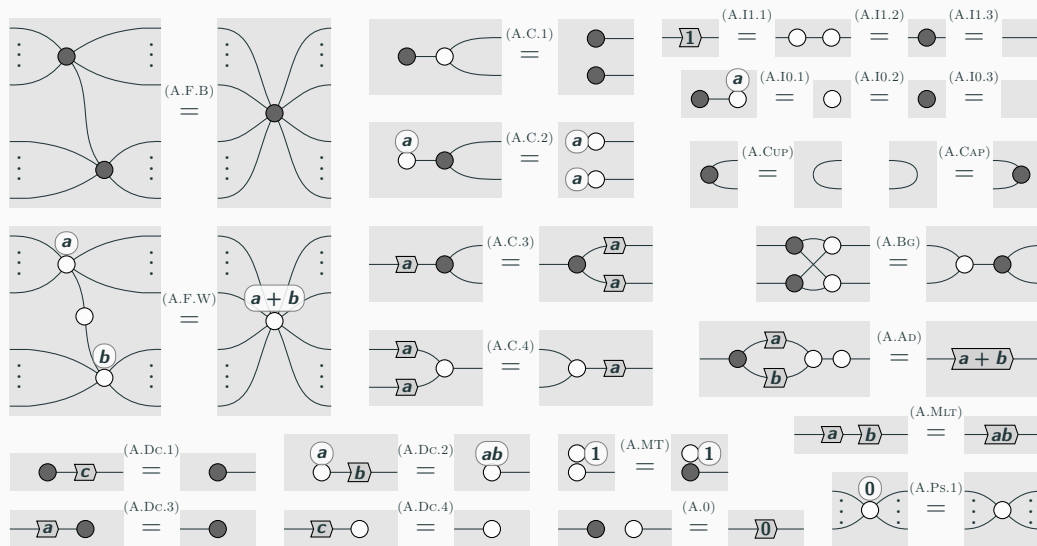
Graphical affine algebra: generators

Let $\text{GAA}_{\mathbb{K}}$ be the diagrammatic language generated by



where $a \in \mathbb{K}$ and $m, n \in \mathbb{N}$, subject to the following equations...

Graphical affine algebra: equations



Graphical affine algebra: interpretation

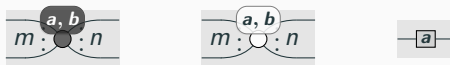
$$\begin{aligned}
 \left[\begin{array}{c} m \vdots n \\ \text{---} \bullet \text{---} \end{array} \right]_{\text{GAA}}^{\text{AR}} &:= \left\{ \left(\begin{bmatrix} a \\ \vdots \\ a \end{bmatrix}, \begin{bmatrix} a \\ \vdots \\ a \end{bmatrix} \right) \in \mathbb{K}^n \oplus \mathbb{K}^m \mid a \in \mathbb{K} \right\} \\
 \left[\begin{array}{c} m \vdots n \\ \text{---} \circ \text{---} \end{array} \right]_{\text{GAA}}^{\text{AR}} &:= \left\{ (\vec{b}, \vec{c}) \in \mathbb{K}^n \oplus \mathbb{K}^m \mid \sum_{j=0}^{n-1} b_j + \sum_{k=0}^{m-1} c_k = a \right\} \\
 \left[\text{---} \boxed{a} \text{---} \right]_{\text{GAA}}^{\text{AR}} &:= \{(b, ab) \mid b \in \mathbb{K}\}
 \end{aligned}$$

Theorem

This is an equivalence of categories $\text{GAA}_{\mathbb{K}} \simeq \text{AffRel}_{\mathbb{K}}$.

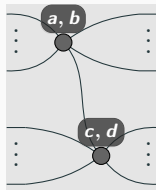
Graphical symplectic algebra: generators

Let $\text{GSA}_{\mathbb{K}}$ be the diagrammatic language generated by

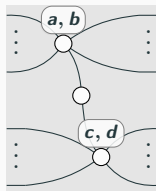
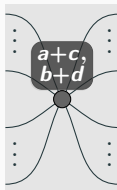


where $a, b \in \mathbb{K}$ and $m, n \in \mathbb{N}$, subject to the equations...

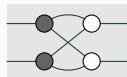
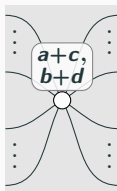
Graphical symplectic algebra: equations



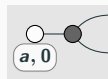
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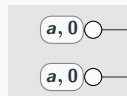
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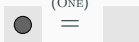
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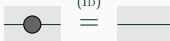
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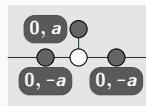
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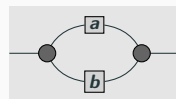
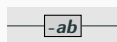
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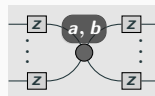
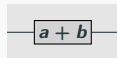
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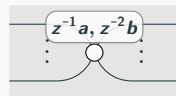
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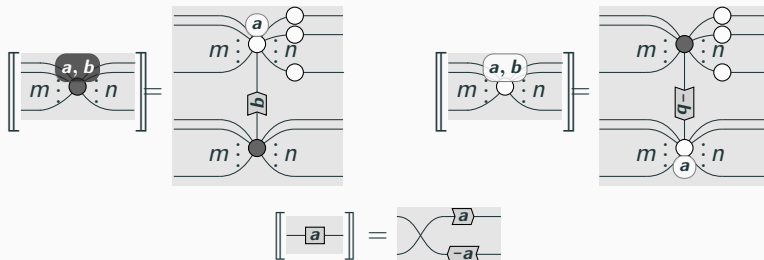
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Graphical symplectic algebra: interpretation

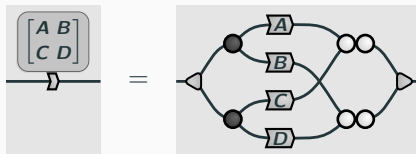


The scalable notation

We add the following syntactic sugar:

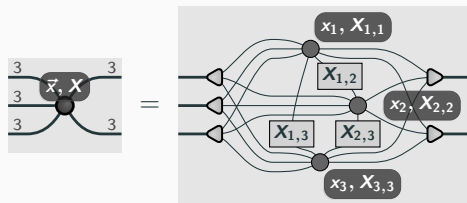
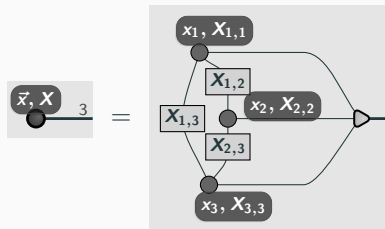


so that we can define **matrix arrows**,



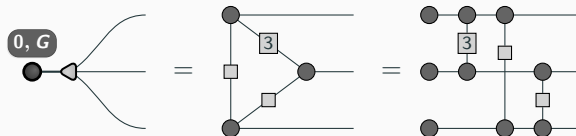
Scalable symplectic spiders

For $\vec{x} \in \mathbb{K}^n$ and *symmetric* $X \in \mathbb{K}^{n \times n}$:

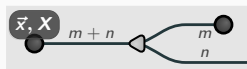


Graph states and graph-like diagrams

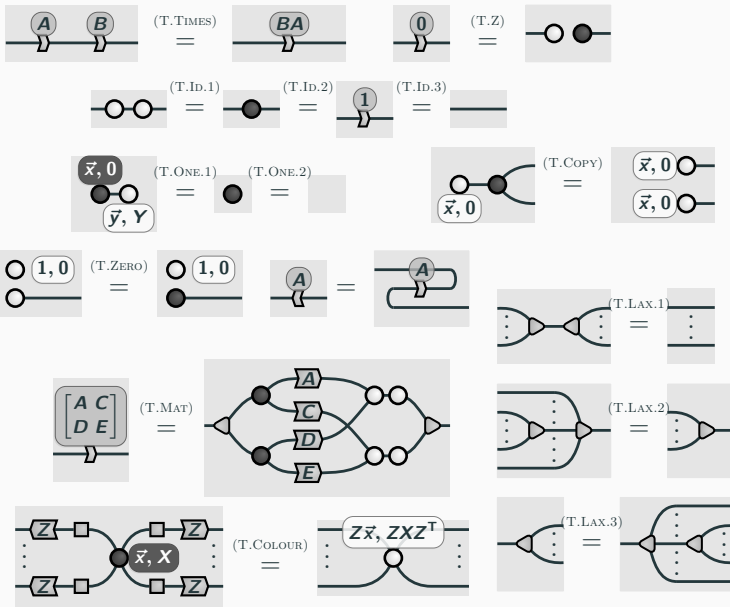
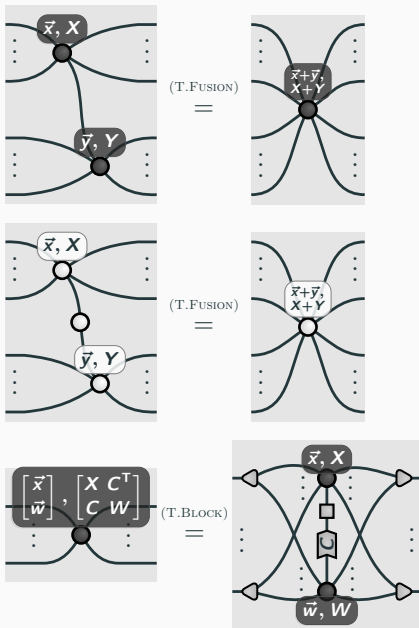
Let G be the adjacency matrix of a graph, then



Graph-like diagrams can therefore be compactly represented as:



Scalable axiomatisation

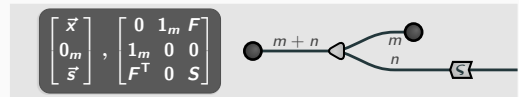


Proposition

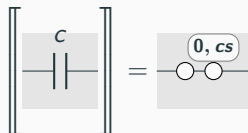
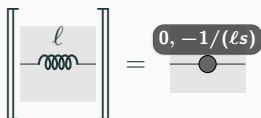
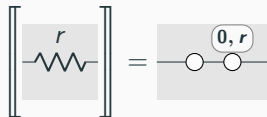
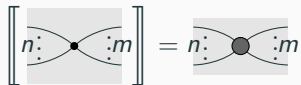
For any invertible $X \in \text{Sym}_m(\mathbb{K})$, $Y \in \text{Sym}_n(\mathbb{K})$, $E \in \text{Mat}_{\mathbb{K}}(n, m)$, $\vec{x} \in \mathbb{K}^m$, and $\vec{y} \in \mathbb{K}^n$:

$$\left[\begin{array}{c} \vec{x} \\ \vec{y} \end{array} \right], \left[\begin{array}{cc} X & E \\ E^T & Y \end{array} \right] \xrightarrow{m+n} \begin{array}{c} m \\ n \end{array} = \left[\begin{array}{c} \vec{y} + EX^{-1}\vec{x} \\ \vec{y} - EX^{-1}E^T \end{array} \right]$$

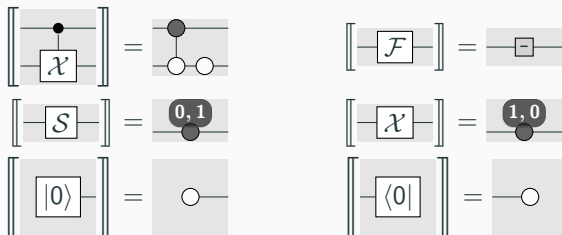
Normalisation procedure

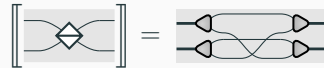
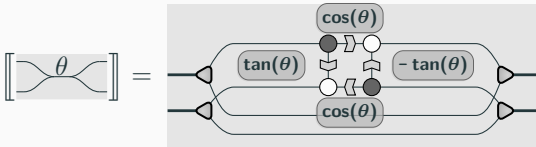
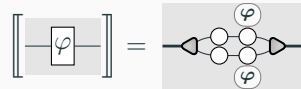
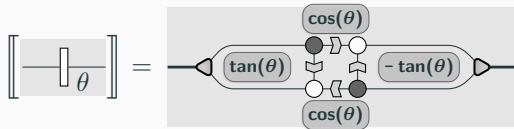


Applications



Stabiliser quantum mechanics





Thanks for listening!